

# Agisoft PhotoScan

Processing Report

16 April 2018



# Survey Data

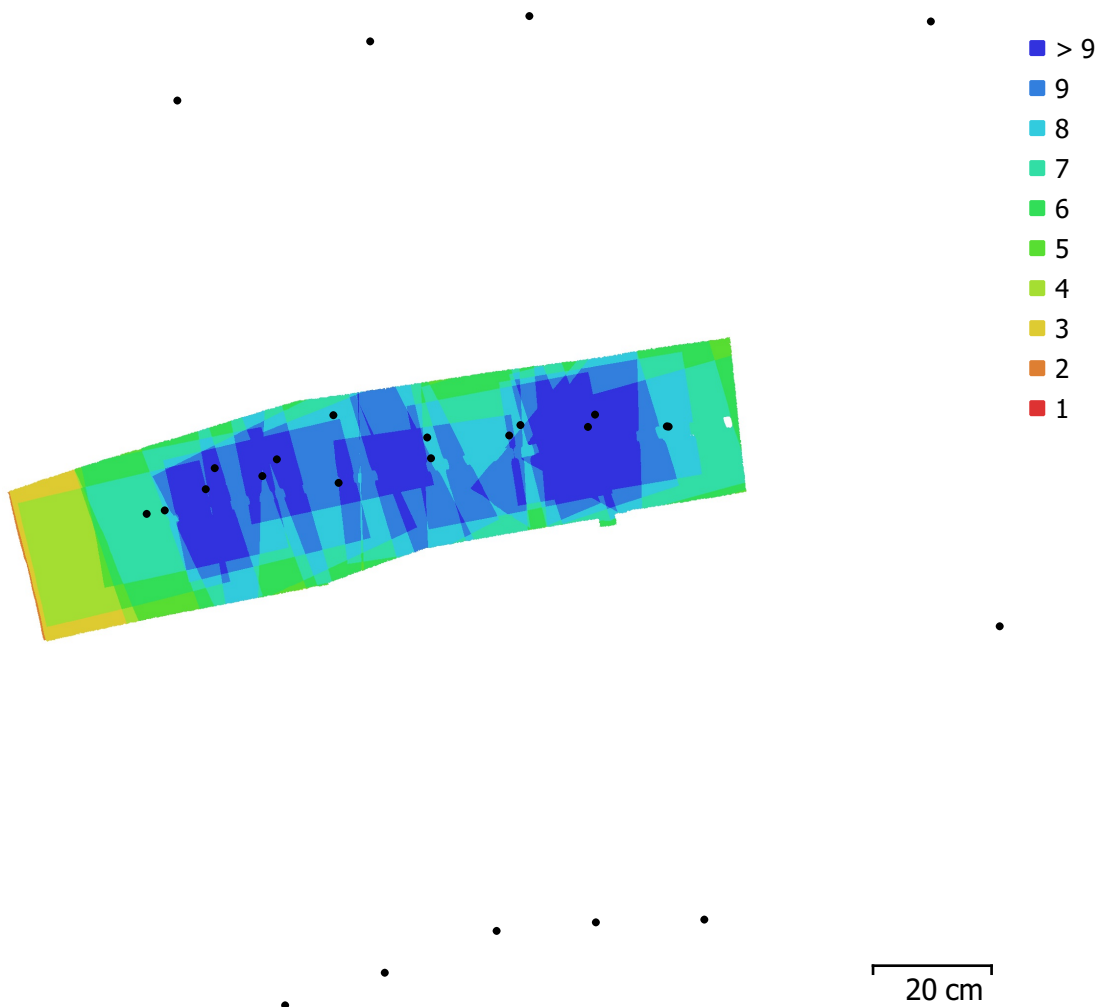


Fig. 1. Camera locations and image overlap.

Number of images:	27	Camera stations:	27
Flying altitude:	88.5 cm	Tie points:	91,284
Ground resolution:	0.0678 mm/pix	Projections:	230,512
Coverage area:	3.43e+03 cm <sup>2</sup>	Reprojection error:	0.604 pix

Camera Model	Resolution	Focal Length	Pixel Size	Precalibrated
NIKON D600 (62 mm)	6034 x 4028	62 mm	5.96 x 5.96 μm	No
NIKON D600 (62 mm)	4028 x 6034	62 mm	5.96 x 5.96 μm	No
NIKON D600 (100 mm)	4028 x 6034	100 mm	5.96 x 5.96 μm	No
NIKON D600 (100 mm)	6034 x 4028	100 mm	5.96 x 5.96 μm	No
NIKON D600 (90 mm)	6034 x 4028	90 mm	5.96 x 5.96 μm	No

Table 1. Cameras.

# Camera Calibration

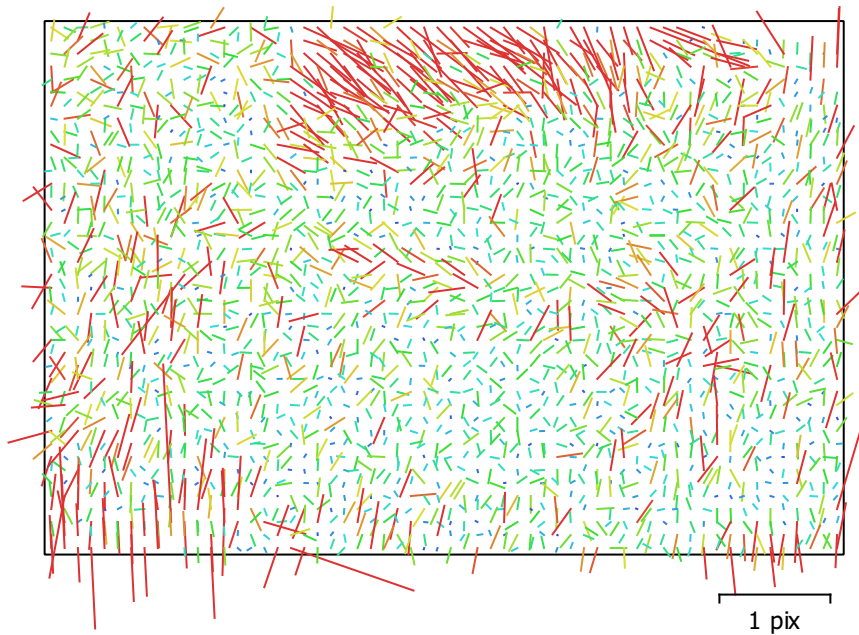


Fig. 2. Image residuals for NIKON D600 (62 mm).

## NIKON D600 (62 mm)

5 images

Type	Resolution	Focal Length	Pixel Size
<b>Frame</b>	<b>6034 x 4028</b>	<b>62 mm</b>	<b>5.96 x 5.96 <math>\mu\text{m}</math></b>
F:	10011.6		
Cx:	-25.944	B1:	6.77166
Cy:	-26.1993	B2:	0.0679776
K1:	-0.0354689	P1:	0.000374132
K2:	0.270336	P2:	0.000645868
K3:	-1.51686	P3:	0
K4:	0	P4:	0

# Camera Calibration

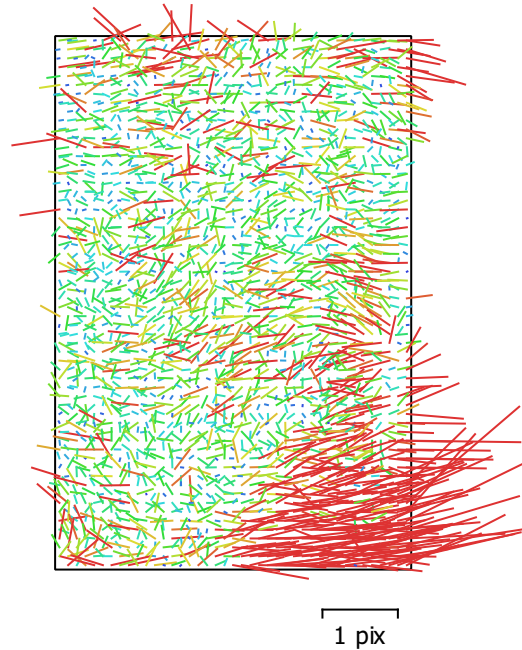


Fig. 3. Image residuals for NIKON D600 (62 mm).

## NIKON D600 (62 mm)

3 images

Type	Resolution	Focal Length	Pixel Size
<b>Frame</b>	<b>4028 x 6034</b>	<b>62 mm</b>	<b>5.96 x 5.96 <math>\mu\text{m}</math></b>
F:	9806.37		
Cx:	21.278	B1:	-9.67033
Cy:	-80.1001	B2:	-4.25667
K1:	-0.0278465	P1:	0.000223861
K2:	0.0708176	P2:	-0.00159528
K3:	-0.581653	P3:	0
K4:	0	P4:	0

# Camera Calibration

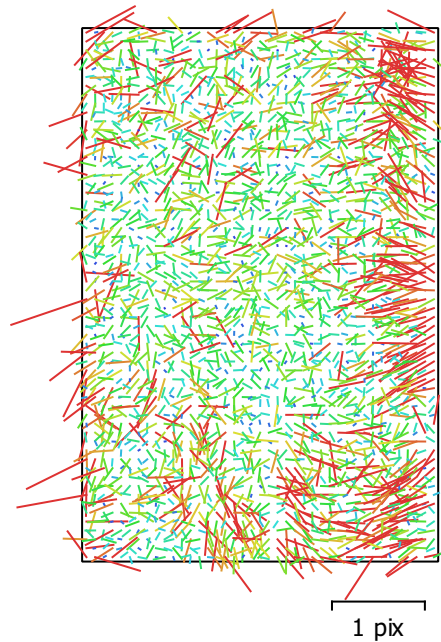


Fig. 4. Image residuals for NIKON D600 (100 mm).

## NIKON D600 (100 mm)

5 images

Type	Resolution	Focal Length	Pixel Size
<b>Frame</b>	<b>4028 x 6034</b>	<b>100 mm</b>	<b>5.96 x 5.96 <math>\mu\text{m}</math></b>
F:	14836.4		
Cx:	-10.8098	B1:	-17.8116
Cy:	-37.8511	B2:	-6.96697
K1:	0.0810166	P1:	-0.000277875
K2:	-2.00059	P2:	0.000115542
K3:	15.9219	P3:	0
K4:	0	P4:	0

# Camera Calibration

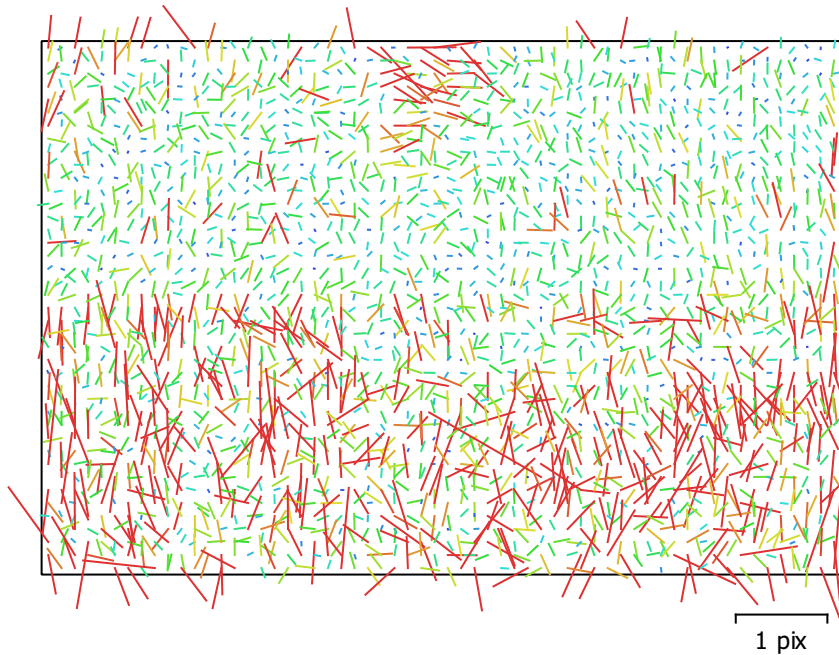


Fig. 5. Image residuals for NIKON D600 (100 mm).

## NIKON D600 (100 mm)

3 images

Type	Resolution	Focal Length	Pixel Size
<b>Frame</b>	<b>6034 x 4028</b>	<b>100 mm</b>	<b>5.96 x 5.96 <math>\mu\text{m}</math></b>
F:	15125.6		
Cx:	2.83776	B1:	8.50529
Cy:	-68.871	B2:	2.74256
K1:	0.0507448	P1:	0.000779426
K2:	-0.963003	P2:	-6.26611e-05
K3:	7.31682	P3:	0
K4:	0	P4:	0

# Camera Calibration

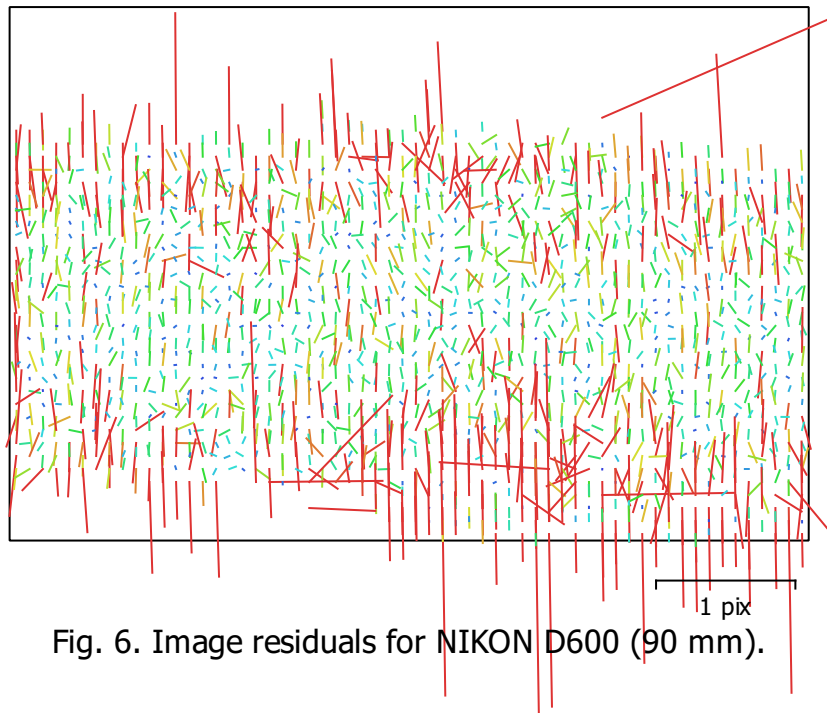


Fig. 6. Image residuals for NIKON D600 (90 mm).

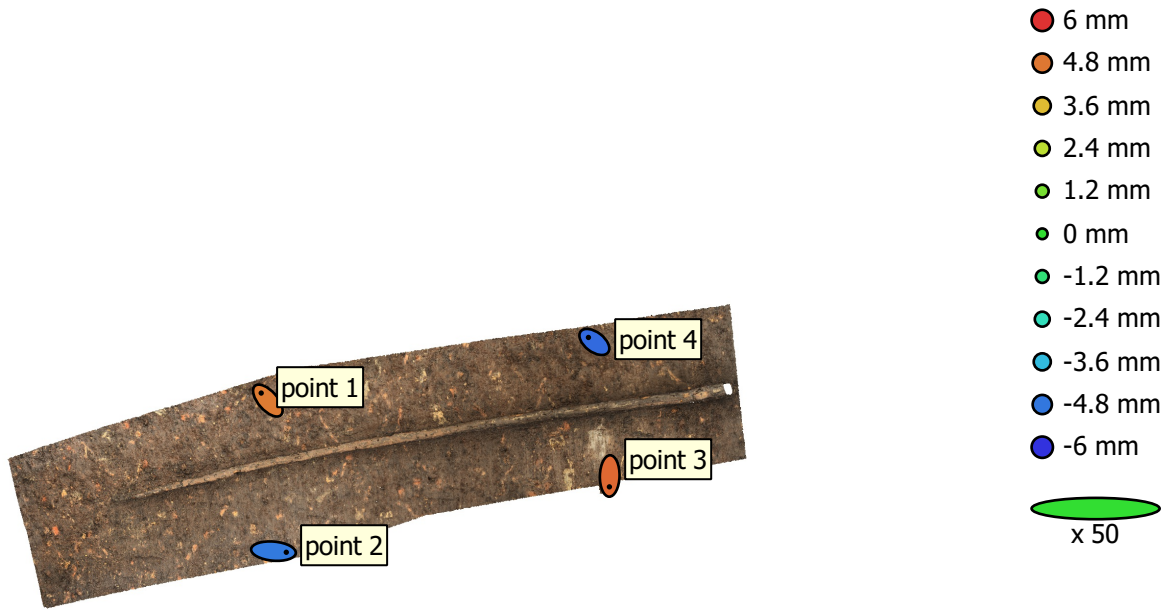
## NIKON D600 (90 mm)

11 images

Type	Resolution	Focal Length	Pixel Size
<b>Frame</b>	<b>6034 x 4028</b>	<b>90 mm</b>	<b>5.96 x 5.96 <math>\mu\text{m}</math></b>
F:	14526.8		
Cx:	32.9432	B1:	-33.2431
Cy:	187.011	B2:	8.80328
K1:	0.0235176	P1:	-0.000507988
K2:	0.0542355	P2:	0.00392319
K3:	-5.70258	P3:	0
K4:	0	P4:	0



# Ground Control Points



● Control points

⊠ Check points

┌───┐  
20 cm

Fig. 7. GCP locations and error estimates.

Z error is represented by ellipse color. X,Y errors are represented by ellipse shape.

Estimated GCP locations are marked with a dot or crossing.

Count	X error (mm)	Y error (mm)	Z error (mm)	XY error (mm)	Total (mm)
4	0.52661	0.473196	4.89265	0.707978	4.94361

Table 2. Control points RMSE.

<b>Label</b>	<b>X error (mm)</b>	<b>Y error (mm)</b>	<b>Z error (mm)</b>	<b>Total (mm)</b>	<b>Image (pix)</b>
point 1	-0.446794	0.506693	4.72457	4.77263	0.956 (9)
point 2	0.865669	-0.0759679	-4.74553	4.82444	0.131 (6)
point 3	-0.0189951	-0.735164	5.05579	5.109	0.010 (7)
point 4	-0.39988	0.304439	-5.03483	5.05986	0.103 (9)
<b>Total</b>	<b>0.52661</b>	<b>0.473196</b>	<b>4.89265</b>	<b>4.94361</b>	<b>0.521</b>

Table 3. Control points.

# Digital Elevation Model

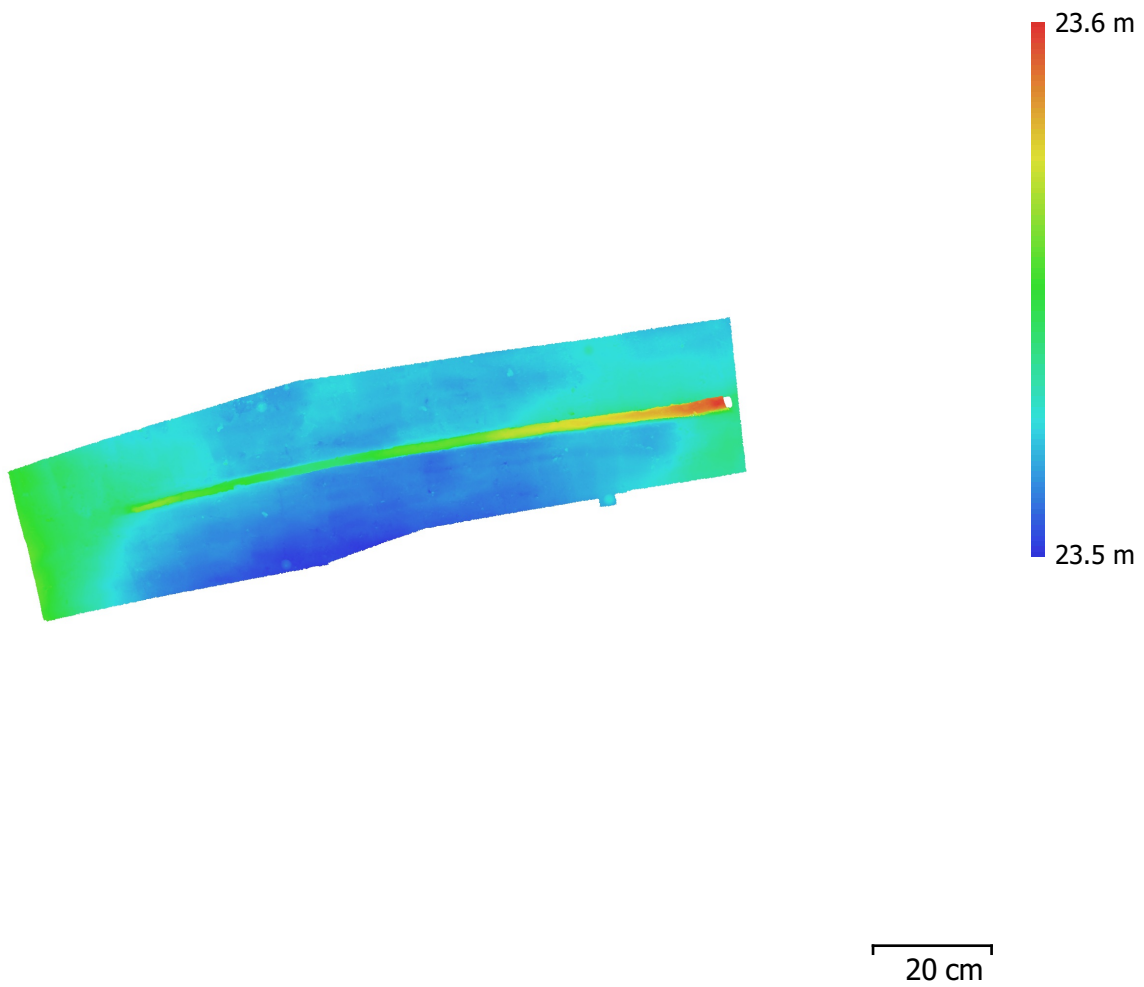


Fig. 8. Reconstructed digital elevation model.

Resolution: 0.136 mm/pix  
Point density: 5.44e+04 points/mm<sup>2</sup>

# Processing Parameters

## General

Cameras	27
Aligned cameras	27
Markers	4
Coordinate system	Local Coordinates (m)
Rotation angles	Yaw, Pitch, Roll

## Point Cloud

Points	91,284 of 100,748
Point colors	3 bands, uint8
Reprojection error	0.603593 (5.78881 max)
Effective overlap	2.60723

### Alignment parameters

Accuracy	High
Generic preselection	Yes
Reference preselection	No
Key point limit	30,000
Filter points by mask	Yes
Matching time	1 minutes 4 seconds
Alignment time	25 seconds

### Optimization parameters

Parameters	f, b1, b2, cx, cy, k1-k3, p1, p2
Optimization time	4 seconds

## Dense Point Cloud

Points	27,093,336
Point colors	3 bands, uint8

### Reconstruction parameters

Quality	High
Depth filtering	Moderate
Dense cloud generation time	8 minutes 13 seconds

## Model

Faces	477,956
Vertices	240,802
Vertex colors	3 bands, uint8
Texture	3,500 x 3,500, 4 bands, uint8

### Reconstruction parameters

Surface type	Arbitrary
Source data	Dense
Interpolation	Enabled
Quality	High
Depth filtering	Moderate
Face count	604,888
Processing time	25 minutes 39 seconds

### Texturing parameters

Blending mode	Mosaic
Texture size	3,500 x 3,500
UV mapping time	5 minutes 45 seconds
Blending time	3 minutes 0 seconds

## Software

Version	1.4.1 build 5925
Platform	Windows 64